

Képletgyűjtemény

A vastagított betűk vektorokat jelölnek.

$$F = \gamma \frac{m_1 m_2}{r^2}, \quad \gamma = 6,67 \cdot 10^{-11} \frac{\text{Nm}^2}{\text{kg}^2}$$

$$r = \frac{mv}{qB}, \quad T = \frac{2\pi m}{qB}$$

$$\mathbf{F} = -\gamma \frac{m_1 m_2}{|\mathbf{r}_2 - \mathbf{r}_1|^3} (\mathbf{r}_2 - \mathbf{r}_1)$$

$$F = -kx, \quad \omega_0 = \sqrt{\frac{k}{m}}$$

$$F = k \frac{q_1 q_2}{r^2}, \quad k = 9 \cdot 10^9 \frac{\text{Nm}^2}{\text{C}^2}$$

$$\sigma = E\varepsilon, \quad \sigma = \frac{dN}{dA}, \quad \varepsilon = \frac{N}{EA}$$

$$e = 1,6 \cdot 10^{-19} \text{ C}$$

$$\Delta \ell = \int_0^\ell \varepsilon dz = \frac{N\ell}{EA}$$

$$\mathbf{F} = k \sum_{i=1}^n \frac{q_0 q_i}{|\mathbf{r} - \mathbf{r}_i|^3} (\mathbf{r} - \mathbf{r}_i)$$

$$k = \frac{EA}{\ell}$$

$$\mathbf{E}(\mathbf{r}) = k \sum_{i=1}^n \frac{q_i}{|\mathbf{r} - \mathbf{r}_i|^3} (\mathbf{r} - \mathbf{r}_i)$$

$$\mathbf{F}(\mathbf{r}) = -\text{grad } U(\mathbf{r}), \quad F_x = -\frac{\partial U(x, y, z)}{\partial x}$$

$$\mathbf{E}(\mathbf{r}) = k \int_{(V')} \frac{dq}{|\mathbf{r} - \mathbf{r}'|^3} (\mathbf{r} - \mathbf{r}')$$

$$W_{1,2} = \int_{\mathbf{r}_1}^{\mathbf{r}_2} \mathbf{F} d\mathbf{r}, \quad W_{1,2} = U_1 - U_2$$

$$U = -mgz$$

$$E_x = k \frac{Qx}{(R^2 + x^2)^{3/2}}$$

$$U = -\frac{\gamma m_1 m_2}{|\mathbf{r}_2 - \mathbf{r}_1|}$$

$$\mathbf{F} = q(\mathbf{E} + \mathbf{v} \times \mathbf{B})$$

$$U = -\frac{\gamma m_1 m_2}{\sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}}$$

$$F = m \frac{v^2}{r}$$

$$U = -\gamma \frac{m_1 m_2}{r_{12}} - \gamma \frac{m_1 m_3}{r_{13}} - \gamma \frac{m_2 m_3}{r_{23}}$$

$$U = \frac{kq_1q_2}{|\mathbf{r}_2 - \mathbf{r}_1|}$$

$$U = \frac{kq_1q_2}{\sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}}$$

$$W_{1,2} = q_0 \int_{\mathbf{r}_1}^{\mathbf{r}_2} \mathbf{E} d\mathbf{r} = U_1 - U_2$$

$$\mathbf{p} = q\mathbf{l}, \quad \mathbf{M} = q\mathbf{l} \times \mathbf{E} = \mathbf{p} \times \mathbf{E}$$

$$M = -pE \sin \theta$$

$$U = -\mathbf{p}\mathbf{E} = -pE \cos \theta, \quad W_{1,2} = pE(\cos \theta_2 - \cos \theta_1)$$

$$V = \frac{U}{q_0}, \quad \Delta V = V_2 - V_1 = - \int_{\mathbf{r}_1}^{\mathbf{r}_2} \mathbf{E} d\mathbf{r}$$

$$\mathbf{E} = -\text{grad } V, \quad E_x = -\frac{\partial V(x, y, z)}{\partial x}$$

$$V = k \sum_{i=1}^n \frac{q_i}{r_i}, \quad V = k \int_{(V)} \frac{dq}{r}$$

$$V(x) = \frac{kQ}{\sqrt{R^2 + x^2}}$$

$$U = \frac{1}{2}kx^2$$

$$U_{\text{rug}} = \frac{1}{2}EA\ell\varepsilon^2, \quad u_{\text{rug}} = \frac{1}{2}\sigma\varepsilon, \quad U_{\text{rug}} = \frac{1}{2} \int_{(V)} \sigma\varepsilon dV$$

$$\dot{Q} = \int_{(A)} \dot{\mathbf{q}} d\mathbf{A}$$

$$\dot{\mathbf{q}} = -\kappa \text{grad } T, \quad \dot{q}_x = -\kappa \frac{\partial T(x, y, z, t)}{\partial x}$$

$$c_p \rho \frac{\partial T}{\partial t} + \text{div } \dot{\mathbf{q}} = \dot{e}$$

$$c_p \rho \frac{\partial T}{\partial t} = \text{div}(\kappa \text{grad } T) + \dot{e}$$

$$\frac{\partial T}{\partial t} = a \left(\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} + \frac{\partial^2 T}{\partial z^2} \right) + \frac{1}{c_p \rho} \dot{e}, \quad a = \frac{\kappa}{c_p \rho}$$

$$\frac{\partial T}{\partial t} = a \left(\frac{\partial^2 T}{\partial r^2} + \frac{1}{r} \frac{\partial T}{\partial r} + \frac{1}{r^2} \frac{\partial^2 T}{\partial \varphi^2} + \frac{\partial^2 T}{\partial z^2} \right) + \frac{1}{c_p \rho} \dot{e}$$

$$\kappa \Delta T + \dot{e} = 0, \quad \Delta T = 0, \quad \frac{d^2 T}{dx^2} = 0$$

$$\dot{\mathbf{q}}|_{\text{felület}} = \alpha(T_{\text{felület}} - T_\infty)$$

$$\left. \frac{dT}{dx} \right|_{\text{felület}} = -\frac{\alpha}{\kappa} (T_{\text{felület}} - T_\infty)$$

$$\dot{q}_x = -\frac{\kappa_i}{d_i} (T_i - T_{i-1}), \quad \dot{q}_x = \frac{T_0 - T_n}{\sum_{i=1}^n \frac{d_i}{\kappa_i}}$$

$$T_1 = T_0 - \dot{q}_x \frac{d_1}{\kappa_1}, \quad T_2 = T_1 - \dot{q}_x \frac{d_2}{\kappa_2}$$

$$\dot{Q}_i = \frac{T_{i-1} - T_i}{R_i} = \frac{\Delta T_i}{R_i}, \quad R_i = \frac{d_i}{\kappa_i A_i}$$

$$\dot{Q} = \frac{\Delta T}{R_{\text{eredő}}} = \frac{T_0 - T_n}{R_1 + R_2 + \dots + R_n}$$

$$\dot{Q}_i \frac{T_1 - T_2}{R_i} = \frac{\Delta T}{R_i}, \quad \dot{Q} = \frac{\Delta T}{R_{\text{eredő}}}$$

$$R_{\text{eredő}} = \frac{1}{\frac{1}{R_1} + \frac{1}{R_2} + \dots + \frac{1}{R_n}}$$

$$T(x) = T_0 + \frac{1}{2} \frac{\dot{e}}{\kappa} \left(\frac{d^2}{4} - x^2 \right), \quad T_{\text{max}} = T_0 + \frac{1}{8} \frac{\dot{e}}{\kappa} d^2$$

$$\frac{d^2 T}{dr^2} + \frac{1}{r} \frac{dT}{dr} = 0, \quad T(r) = T_1 + \frac{T_1 - T_2}{\ln \frac{r_1}{r_2}} \ln \frac{r}{r_1}$$

$$\dot{q}_r = -\kappa \frac{T_1 - T_2}{\ln \frac{r_1}{r_2}} \frac{1}{r}, \quad \dot{Q} = -\kappa 2\pi L \frac{T_1 - T_2}{\ln \frac{r_1}{r_2}}$$

$$\dot{Q} = 2\pi L \frac{T_0 - T_n}{\sum_{i=1}^n \frac{1}{\kappa_i} \ln \frac{r_i}{r_{i-1}}}$$

$$T_i = T_{i-1} + \frac{\dot{Q}}{2\pi L \kappa_i} \ln \frac{r_{i-1}}{r_i}$$